

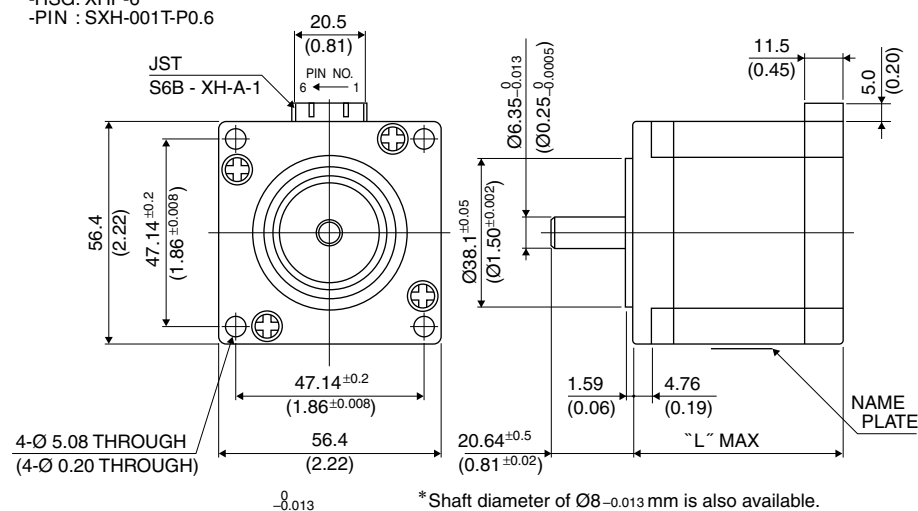
# 56 0.9°

# 23KY-K

# 0.9°

## Outline

- LEAD WIRE SIDE
  - HSG: XHP-6
  - PIN : SXH-001T-P0.6



Hybrid

UNIT: mm  
(inch)

	"L"
23KY-K2**	42 (1.65)
23KY-K0**	54 (2.13)
23KY-K7**	76 (2.99)

### PIN NO. vs. PHASE

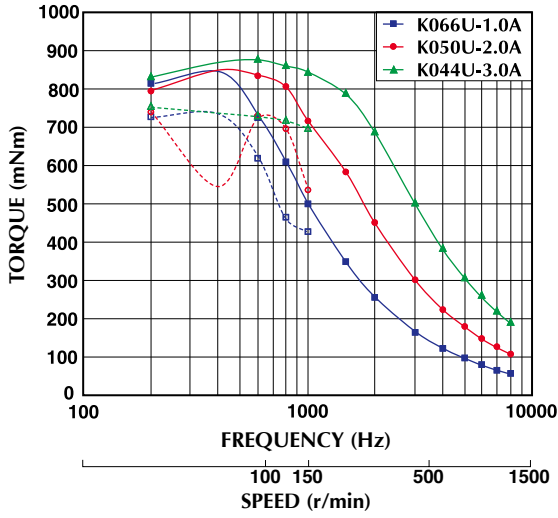
(PHASE)	A	A COM	$\bar{A}$	B	B COM	$\bar{B}$
(PIN NO.)	1	2	3	4	5	6

## Specifications

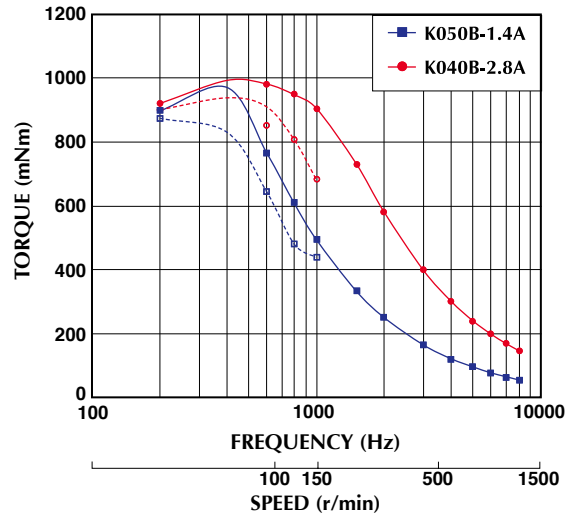
Model	Step Angle (deg)	Drive Sequence	Rated Current (A)	Resistance (Ohms)	Holding Torque (mNm)	Inductance (mH)	Rotor Inertia (g · cm <sup>2</sup> )	Detent Torque (mNm)	Mass (g)
23KY-K066U	0.9	UNI-POLAR	1.0	7.0	890	19.0	200	43	680
23KY-K050U	0.9	UNI-POLAR	2.0	1.8	890	5.6	200	43	680
23KY-K044U	0.9	UNI-POLAR	3.0	0.9	890	2.4	200	43	680
23KY-K267U	0.9	UNI-POLAR	1.0	6.3	470	10.0	120	22	470
23KY-K251U	0.9	UNI-POLAR	1.8	1.6	470	3.2	120	22	470
23KY-K244U	0.9	UNI-POLAR	3.0	0.7	470	1.1	120	22	470
23KY-K762U	0.9	UNI-POLAR	1.0	8.6	1250	23.0	360	50	1050
23KY-K748U	0.9	UNI-POLAR	2.0	2.3	1250	6.5	360	50	1050
23KY-K743U	0.9	UNI-POLAR	3.0	1.1	1250	2.9	360	50	1050
23KY-K050B	0.9	BI-POLAR	1.4	3.6	1050	20.0	200	43	680
23KY-K040B	0.9	BI-POLAR	2.8	0.9	1050	3.8	200	43	680
23KY-K251B	0.9	BI-POLAR	1.4	3.0	580	11.0	120	22	470
23KY-K241B	0.9	BI-POLAR	2.8	0.8	580	2.4	120	22	470
23KY-K748B	0.9	BI-POLAR	1.4	4.5	1580	24.0	360	50	1050
23KY-K740B	0.9	BI-POLAR	2.8	1.35	1580	5.7	360	50	1050

## Torque/Speed Characteristics

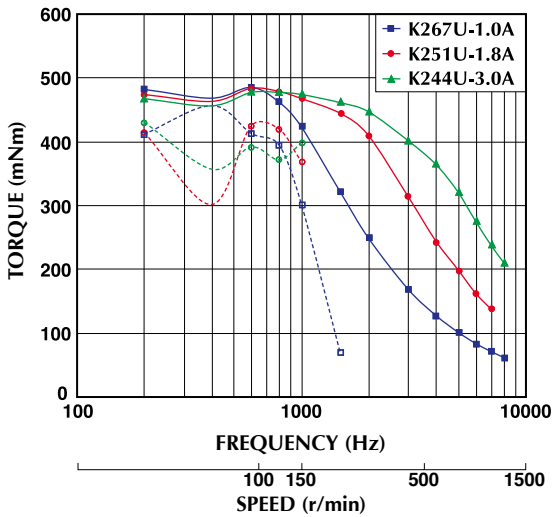
Model No: 23KY-K066U,K050U,K044U  
 Driver: Chopper Dual  
 Supply Voltage: 24.0 (Volt)



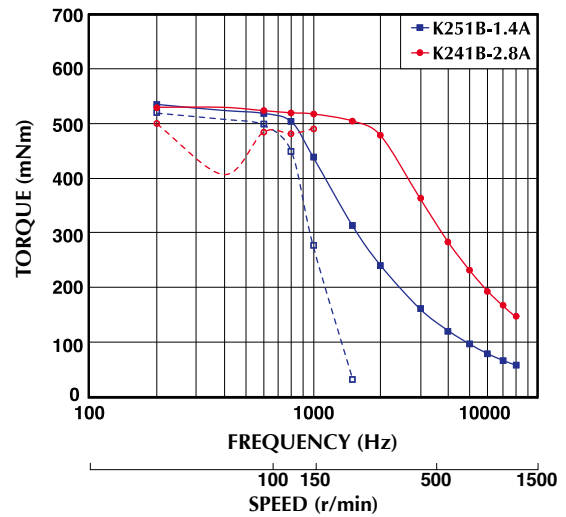
Model No: 23KY-K050B,K040B  
 Driver: Chopper Dual  
 Supply Voltage: 24.0 (Volt)



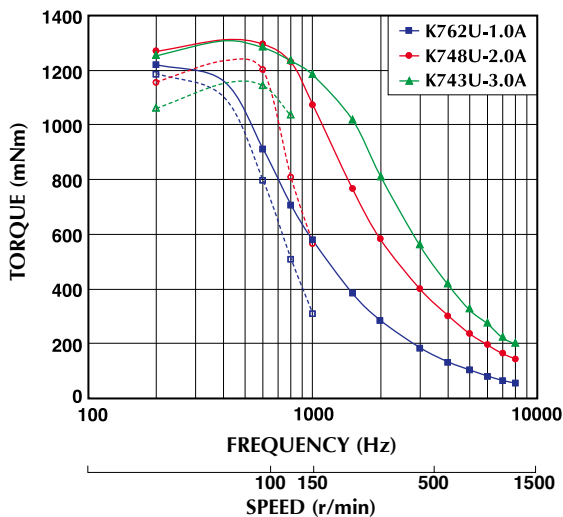
Model No: 23KY-K267U,K251U,K244U  
 Driver: Chopper Dual  
 Supply Voltage: 24.0 (Volt)



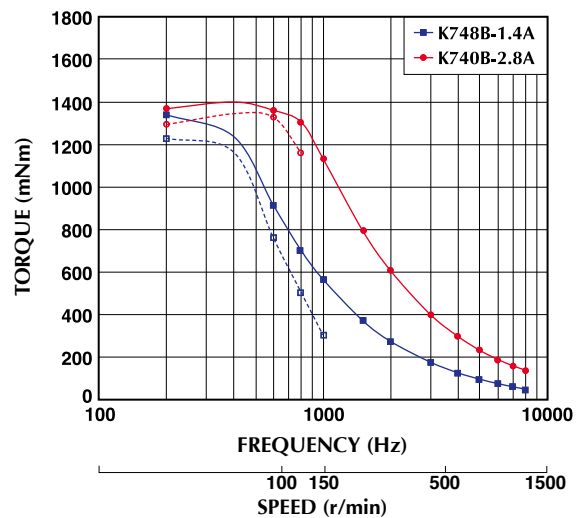
Model No: 23KY-K251B,K241B  
 Driver: Chopper Dual  
 Supply Voltage: 24.0 (Volt)



Model No: 23KY-K762U,K748U,K743U  
 Driver: Chopper Dual  
 Supply Voltage: 24.0 (Volt)



Model No: 23KY-K748B,K740B  
 Driver: Chopper Dual  
 Supply Voltage: 24.0 (Volt)



— : PULL OUT  
 - - - : PULL IN

Torque/Speed characteristics are for reference only and it may change when operated at different drive conditions.